

Bounded Buffer (Hoare)

```
get() {  
    lock.acquire();  
    while (mem == 0)  
        empty.wait(&lock);  
    item = buf[front];  
    front = front++ % size;  
    mem--;  
    full.signal();  
    lock.release();  
    return item;  
}
```

```
put(item) {  
    lock.acquire();  
    while (mem == size)  
        full.wait(&lock);  
    buf[last] = item;  
    last = last++ % size;  
    mem++;  
    empty.signal();  
    lock.release();  
}
```

Bounded Buffer (Mesa)

```
get() {  
    lock.acquire();  
    if (mem == 0 || !nextGet.empty()) {  
        self = createCondition();  
        nextGet.append(self);  
        do self.wait(&lock);  
        while (mem == 0);  
        nextGet.remove(self);  
        destroyCondition(self);  
    }  
    ...
```

```
        item = buf[front];  
        front = front++ % size;  
        mem--;  
        if (!nextPut.empty())  
            nextPut.first() → signal();  
        lock.release();  
        return item;  
    }
```

Bounded Buffer (Semaphore e lock)

```
get() {  
    empty.P();  
    mutex.P();  
    item = buf[front];  
    front = front++ % size;  
    mutex.V();  
    full.V();  
    return item;  
}
```

```
put(item) {  
    full.P();  
    mutex.P();  
    buf[last] = item;  
    last = last++ % size;  
    mutex.V();  
    empty.V();  
}
```

Condition Variables (Semaphore)

```
wait(lock) {  
    sem = createSemaphore();  
    waiting.append(sem);  
    lock.release();  
    sem.P();  
    destroySemaphore(sem);  
    lock.acquire();  
}
```

```
signal() {  
    if (!waiting.empty()) {  
        sem = waiting.remove();  
        sem.V();  
    }  
}
```

Lock

```
LockAcquire() {  
    disableInterrupts();  
    if (val == BUSY) {  
        waiting.add(myTCB);  
        suspend();  
    }  
    else  
        val = BUSY;  
    enableInterrupts();  
}
```

```
LockRelease() {  
    disableInterrupts();  
    if (!waiting.empty()) {  
        thTCB = waiting.remove();  
        readyList.append(thTCB);  
    }  
    else  
        val = FREE;  
    enableInterrupts();  
}
```

Spinlock

```
spinlockAcquire(&spinlockvalue) {  
    LOOP: TSL R3, &spinlockvalue  
        CMP R3, #BUSY  
        BEQ LOOP  
    END  
}
```

```
spinlockRelease(&spinlockvalue) {  
    MOV #FREE, &spinlockvalue  
    MFENCE // memory barrier  
}
```

Semafori con spinlock

P(Sem) {

disable Interrupts();

spinlock Acquire (& spinlock);

if (sem.val == 0) {

waiting.add(myTCB);

suspend (& spinlock);

}

else

sem.val --;

spinlock Release (& spinlock);

enable Interrupts();

}

V(Sem) {

disable Interrupts();

spinlock Acquire (& spinlock);

if (!waiting.empty()) {

thTCB = waiting.remove();

readyList.append(thTCB);

}

else

sem.val ++;

spinlock Release (& spinlock);

enable Interrupts();

}